— KUBIC-NII Joint Seminar on Bioinformatics 2012 —

Translating Process Hitting models to Thomas' modeling with ASP

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AtlanSTIC sojourn financed by NII & Centrale Initiatives

A multi-team topic

Inoue Laboratory (NII): Constraint Programming, Systems Biology MeForBio (IRCCyN, ÉCN): Formal Methods for Bioinformatics AMIB (LIX, Polytechnique): Algorithms and Models for Integrative Biology



Katsumi INOUE
Professor & team leader

Inoue Laboratory



Loïc PAULEVÉ Post-doc

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Olivier ROUX
Professor & team leader



Morgan MAGNIN Associate professor

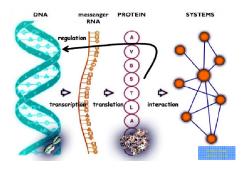


Maxime FOLSCHETTE 1st year PhD student

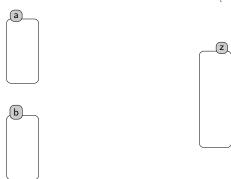
MeForBio

Context and Aims

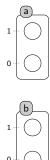
Algebraic modeling to study complex dynamical biological systems:

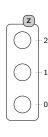


- Historical model: René Thomas' modeling
- New developed model: Process Hitting
- → Allow efficient translation between models



Sorts: components a, b, z

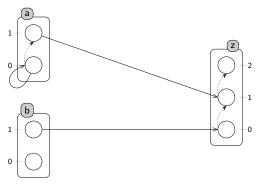




Sorts: components a, b, z

Processes: local states / levels of expression z₀, z₁, z₂

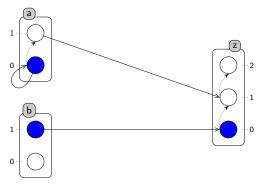
The Process Hitting modeling [PMR12-MSCS]



Sorts: components a, b, z

Processes: local states / levels of expression z₀, z₁, z₂

Actions: dynamics $b_1 o z_0
ightharpoonup z_1$, $a_0 o a_0
ightharpoonup a_1$

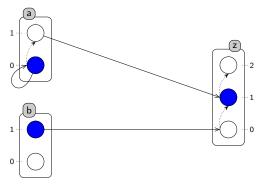


Sorts: components a, b, z

Processes: local states / levels of expression z_0 , z_1 , z_2

Actions: dynamics $b_1 o z_0
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States: sets of active processes $\langle a_0, b_1, z_0 \rangle$

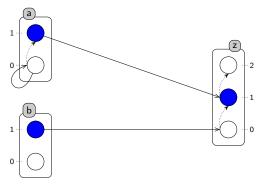


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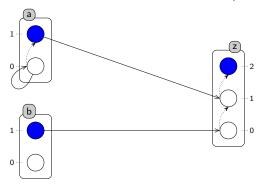
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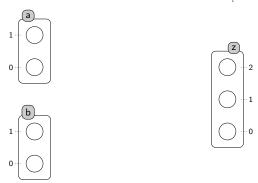


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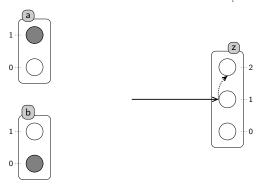
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States: sets of active processes $\langle a_1, b_1, z_2 \rangle$

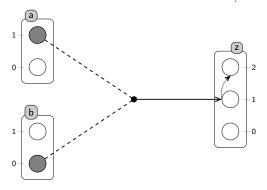


How to introduce some cooperation between sorts?

The Process Hitting modeling [PMR12-MSCS]

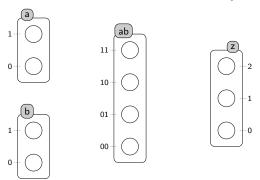


How to introduce some **cooperation** between sorts? $a_1 \wedge b_0 \rightarrow z_1 \upharpoonright z_2$

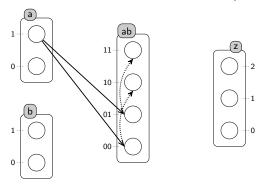


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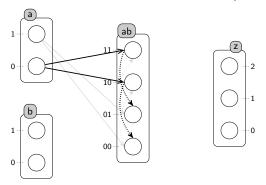
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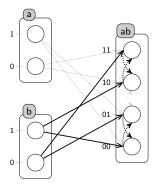
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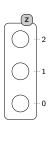


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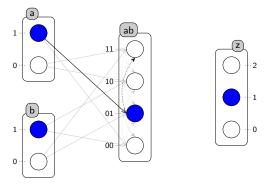


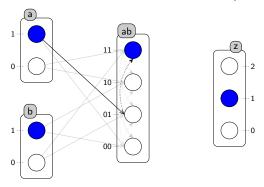


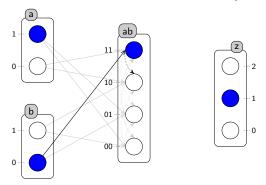
How to introduce some **cooperation** between sorts? $a_1 \wedge b_0 \rightarrow z_1 \stackrel{?}{\vdash} z_2$ Solution: create a cooperative sort

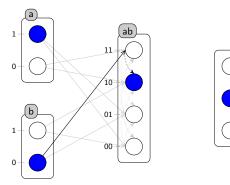
$$a_1 \wedge b_0 \rightarrow z_1 \upharpoonright z_2$$

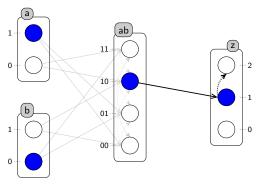
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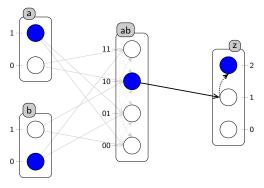




Solution: create a **cooperative sort** ab

We can express any kind of cooperation $a_1 \wedge b_0$

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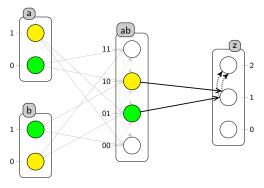


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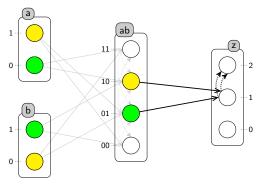
 $a_1 \wedge b_0$



How to introduce some **cooperation** between sorts? $a_1 \wedge b_0 \rightarrow z_1 \stackrel{?}{\vdash} z_2$

Solution: create a cooperative sort

We can express any kind of cooperation $a_1 \wedge b_0$, $a_1 \oplus b_1$

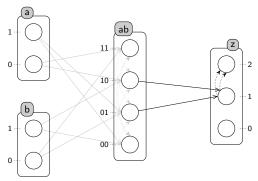


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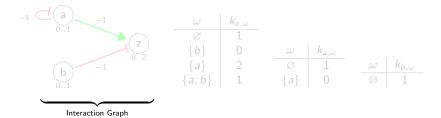
Drawbacks: complexity, temporal shift



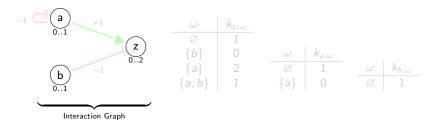
The Process Hitting framework:

- Dynamic modeling with an atomistic point of view
- Efficient static analysis (fixes points, reachability)
- Possible extensions (stochasticity, priorities)
- Useful for the study of large bioinformatics systems

Historical bio-informatics model for studying genes interactions Widely used and well-adapted to represent dynamic gene systems



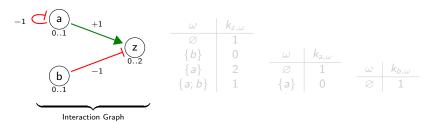
Interaction Graph: structure of the system (genes & interactions)



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Nodes: genes

- \rightarrow Name a, b, z
- \rightarrow Possible values (levels of expression) 0..1, 0..2



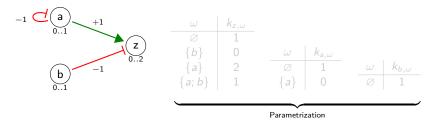
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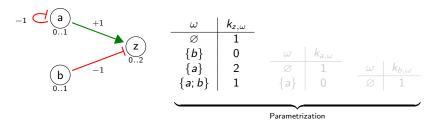
- \rightarrow Name a, b, z
- \rightarrow Possible values (levels of expression) 0..1, 0..2

Edges: interactions

- \rightarrow Type (activation or inhibition) + / -
- ightarrow Threshold

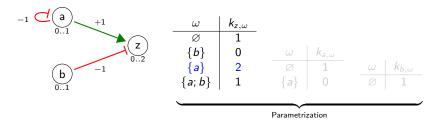


Parametrization: strength of the influences (evolution tendencies)



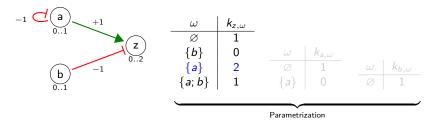
Parametrization: strength of the influences (evolution tendencies)

- ightarrow To any set of predecessors ightharpoonup
- ightarrow Corresponds a **parameter** $k_{x,\omega}$



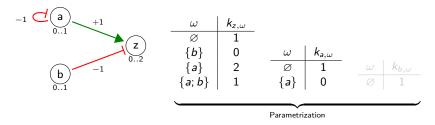
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- ightarrow To any set of predecessors
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- " $k_{z,\{a\}}=2$ " means: "z tends to 2 when $a\geq 1$ and b<1"



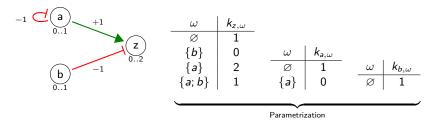
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Parametrization: strength of the influences (evolution tendencies)

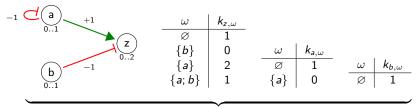
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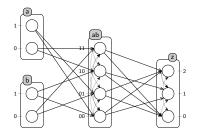
René Thomas' Modeling [RCB08]

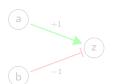


Biological Regulatory Network

- \rightarrow All needed information to run the model or study its dynamics:
 - Build the State Graph
 - Find reachability properties
 - Find fixed points or attractors
 - Other properties...

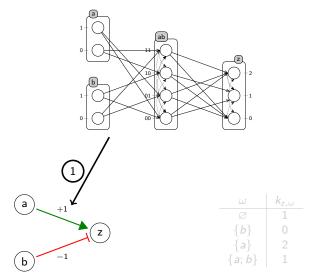
Inferring Thomas' Model



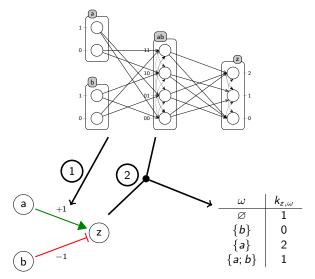


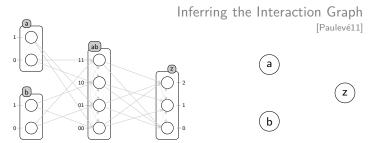
ω	$k_{z,\omega}$
Ø	1
{ <i>b</i> }	0
{a}	2
$\{a; b\}$	1

Inferring Thomas' Model



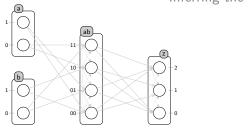
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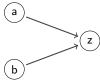




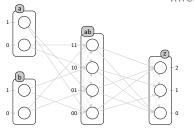
- Inputs: a Process Hitting model and a list of genes

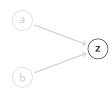
 → distinguish cooperative sorts from sorts modeling real genes
- Output: An interaction graph with all information:
 - ightarrow edges, signs and thresholds
- Difficulties: The Process Hitting is more atomistic than Thomas' modeling
- Idea: Enumeration of the possible configurations



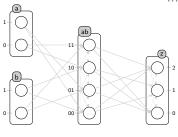


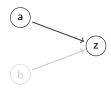
• Determine possible influences $(a \rightarrow z, b \rightarrow z)$



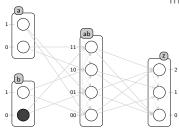


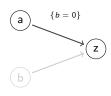
- Determine possible influences $(a \rightarrow z, b \rightarrow z)$
- For each gene [z]



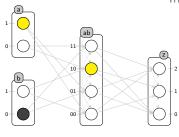


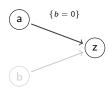
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- For each gene [z], consider one predecessor [a]



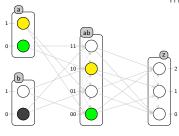


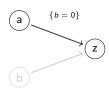
- Determine possible influences $(a \rightarrow z, b \rightarrow z)$
- For each gene [z], consider one predecessor [a]
- Consider a configuration of all other predecessors $[\{b=0\}]$



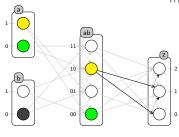


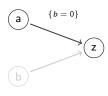
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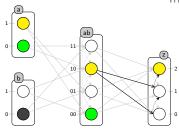


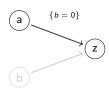
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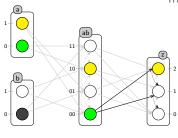


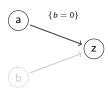
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 - Determine the set of focal (i.e. stable) processes of z



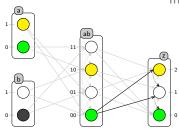


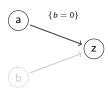
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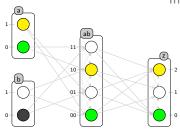


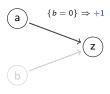
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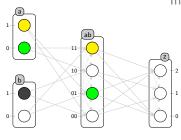
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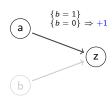




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 - Comparing the sets of focal processes gives the influence

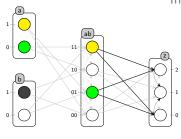
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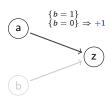




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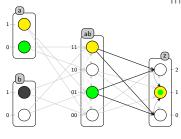
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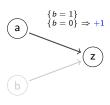




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- For each gene [z], consider one predecessor [a]
- Consider a configuration of all other predecessors $[\{b=1\}]$
 - For each process of a:
 - Inherit the current configuration to the cooperative sorts
 - Determine the set of focal (i.e. stable) processes of z
 - Comparing the sets of focal processes gives the influence

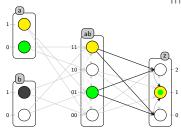
$$\{b=0\} \rightarrow a_0 < a_1 \text{ and } \{z_0\} \preccurlyeq \{z_2\} \Rightarrow \text{activation (+) \& threshold} = 1$$

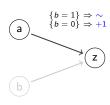




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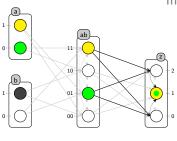
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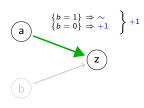




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If possible, determine the general influence of a on z

Inferring the Interaction Graph Implementation & Results

Programming in ASP:

- Formal mathematical definitions → ASP
- Use of aggregates (enumeration = 1 active process per sort)

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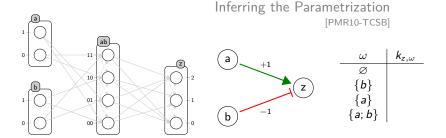
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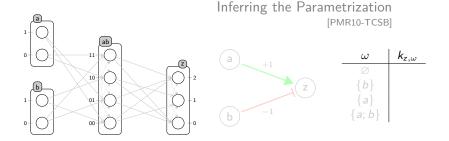
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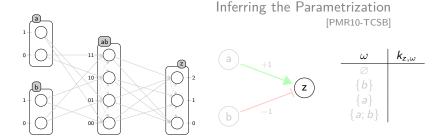
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Results:

- Fast execution for "well-shaped" models (execution time < 1s for a 40 genes model)
- Very slow execution for "bad-shaped" models (with too many predecessors for some genes)

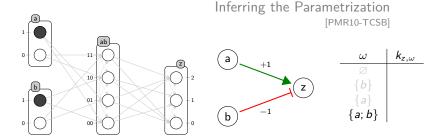




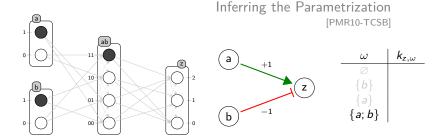


Similar approach than Interaction Graph Inference (focal processes)

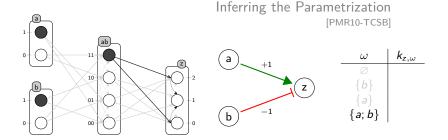
• For each gene [z]



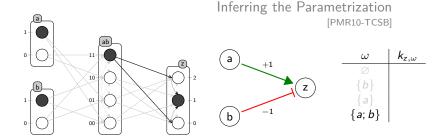
- For each gene [z]
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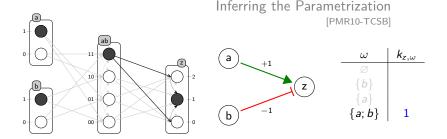
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- For each configuration of active predecessors $[\omega = \{a; b\}]$
 - Find the set of focal processes of the gene $[\{z_1\}]$
 - If this set respects some conditions (attractor, interval)
 - \rightarrow Then we have found the parameter $\Rightarrow k_{z,\{a,b\}} = 1$

 $Translating\ Process\ Hitting\ to\ Thomas -- 2012/04/26:\ Translating\ a\ Process\ Hitting\ Model\ to\ Thomas'\ Modeling$

Inferring the Parametrization Implementation & Results

Same implementation scheme than Interaction Graph Inference: OCaml translation (with Pint) to ASP and ASP execution

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Same implementation scheme than Interaction Graph Inference: OCaml translation (with Pint) to ASP and ASP execution

Results:

- Very fast execution
- May give incomplete results for incomplete models
 - \rightarrow Give all possible parametrizations?

Work Summary

- Inference of the complete Interaction Graph
 - \rightarrow Exhaustive approach to find the mutual influences
- Inference of the possibly partial Parametrization
 - \rightarrow Exhaustive approach to find the necessary parameters
- Rules to auto-detect the cooperative sorts
 - → The Process Hitting model is the only input

Future Work

- Work on complete Parametrizations search
 - → List all compatible parametrizations given some constraints
- Work on the Projections Approach
 - → Idea: model reduction (cooperative sorts removal)
 - → Alternative to the exhaustive approach
 - → Lower complexity?

Conclusion

Existing translation: René Thomas \leadsto Process Hitting

New translation: Process Hitting → René Thomas

- → New **formal link** between the two models
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Thank you

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